# Interface board features

Outputs from the DSP:

1. 3x PWM signals
2. 1x enable signals
   1. To activate drivers
3. Signal to show DSP is ON

Inputs to DSP:

1. 3x encoder signals
2. 3x current measurements
3. 1x voltage measurement
   1. Maybe 2, if we want to measure at both battery packs
4. 1x torque pedal

LEDs:

1. On enable signal to drivers
2. On ON-signal from DSP
3. On every supply line
4. On move-enable
5. On all extra switches
6. 3x extra for general purpose

Switches:

1. Movement Enable
2. OL/CL selection

Buttons:

1. Speed/torque reference selection
2. 2x cruise control speed selection
3. Wheel anti-slip
4. Regenerative breaking

Potentiometers:

1. Speed/torque reference
2. Break reference
3. 3x spares with extra connectors

Additional circuits:

1. 1x Voltage sensor circuit
2. 3x current sensor circuit
3. 3x voltage dividers for encoder signal

Power supplies:

1. 24V 🡪 +/- 15V
   1. Sensor opamp
   2. Current sensor
2. 24V 🡪 5V
   1. Output of voltage sensor
   2. Potmeters
   3. DSP
3. 5V 🡪 5V (Isolated)
   1. Input of voltage sensor

Test points:

1. 3x current
2. 1x voltage
3. Inverter output ¿?
4. Inputs and outputs from interface board can be directly measured in the dsp pcb (pots, switches, encoder…)

Other considerations:

1. Add relay+switch to be able to activate/deactivate fan